

# A Fully Automated Workflow for Gyrolab Assays

Christoph Köhler, Angela Nauer, Elisabeth Friedhoff, Milan Vagaday, Michael Gröschl, Petra Struwe

Celerion Switzerland AG, 8320 Fehraltorf, Switzerland

Download Poster

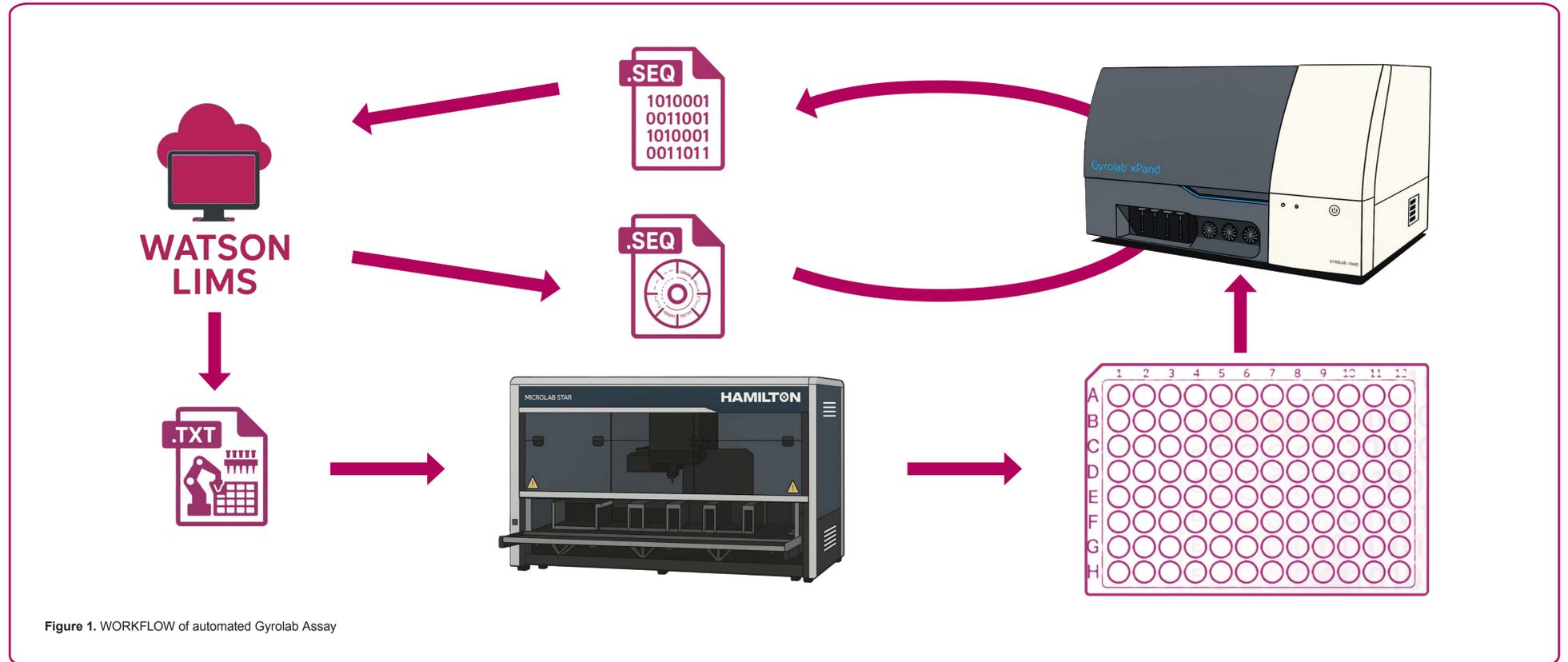


Figure 1. WORKFLOW of automated Gyrolab Assay

## INTRODUCTION

### Implementing a High-Throughput, Regulatory-Compliant Workflow

#### Gyrolab platform

- Microfluidic disk with nanocolumns as carrier
- Reduces matrix effects and improves selectivity
- Rapid turnaround 1 hour per CD

#### Watson LIMS

- Sample tracking, run planning and evaluation

#### Hamilton STARline pipetting robot

- Worklist driven pipetting robot with barcode scanning capability
- Pressure curve monitoring for reliable and compliant pipetting

## WORKFLOW

### 1) Watson LIMS analytical run planning

- Sample planning on 96-well plate
- Export of worklist 📄 for Sample Pipetting on Hamilton robot
- Export of sequence file 📄 for sample positioning on Gyrolab

### 2) Hamilton STAR robot

- Load worklist from Watson LIMS
- Robot pipettes samples according to worklist

### 3) Gyrolab xPand

- Load sequence file from Watson
- Load 96 well sample plates from Hamilton robot
- After run is finished the sequence file filled with the raw data 📄 is saved on a secured server location

### 4) Watson LIMS run evaluation

- Raw data filled sequence file uploaded for evaluation

## AUTOMATION OBJECTIVE

- Fully automated workflow from sample identification to evaluation
- Integration of run setup and evaluation in existing Watson LIMS processes and data flows
- Worklist driven sample pipetting using Hamilton STAR robot
- Sequence file-based run execution on Gyrolab xPand

## IMPROVEMENTS

#### Watson LIMS setup

- Optimized study setup in Watson LIMS for an automated dataflow and process execution.

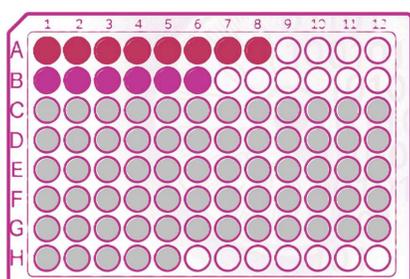
#### Gyrolab xPand and software

- The Gyrolab xPand can be used perfectly standalone with the supplied software but is now fully integrated into our existing dataflows and processes.

## CHALLENGES

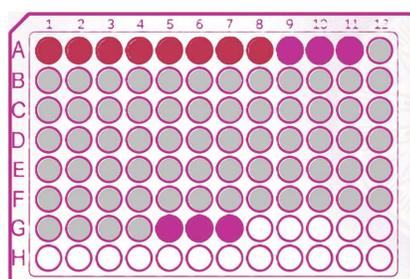
### Gyrolab Run Planning

The Gyrolab planning algorithm assigns samples by row, separating **standards**, **unknowns** and **QCs**. This setup follows an alternative arrangement to the QC bracketing approach described in ICH M10.



Assigned placement on 96 well plate by Gyrolab algorithm:

- **Standards** in row A
- **QCs** in row B
- Unknowns separated



Updated placement according to Watson LIMS run planning following Celerion standardized run setup.

- **Standards** in row A
- First set of **QCs** bracketing Unknowns with second set of **QCs**

## RESULTS & CONCLUSION

#### Regulatory compliant: ICH M10, FDA 21 CFR Part 11

- **Fully automated:** minimal human interaction
- **High throughput:** up to 5 CDs per batch
- **Reagents & Samples:** volume efficient workflow

#### Straight Forward — Highly Efficient!

The implemented solution significantly reduces manual handling and repetitive tasks, enabling seamless integration with Watson LIMS and establishing a robust, regulatory-compliant immunoassay workflow.

## REFERENCES

Nauer, A., Friedhoff, E., Köhler, C., Vagaday, M., & Gröschl, M. (2025). A fully automated workflow for Gyrolab assays. White paper, Celerion Switzerland AG.